



A homoclinic hierarchy

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Communicated by A.P. Fordy

Abstract

Homoclinic bifurcations in autonomous ordinary differential equations provide useful organizing centres for the analysis

AMS classification: 58F13; 58F14

Keywords: Bifurcation; Homoclinic orbit; Chaos

A homoclinic orbit of an autonomous ordinary differential equation is a trajectory $x_H(t)$ which exists at $\mu = \mu_H$. If this is the case we have a homoclinic bifurcation. In typical (e.g. non-Hamiltonian) systems a homoclinic orbit is not a structurally stable feature. In fact, for a generic family of functions $f(x, \mu)$ there is no homoclinic orbit close to the original one. This is because a homoclinic orbit, although the net effect of the bifurcation is to create a homoclinic orbit, recent work has been stimulated by a series of papers [1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85, 86, 87, 88, 89, 90, 91, 92, 93, 94, 95, 96, 97, 98, 99, 100]. In certain conditions described below, there is chaotic behaviour. In fact, for a generic family of functions $f(x, \mu)$ there is no homoclinic orbit close to the original one, although the net effect of the bifurcation is to create a homoclinic orbit. This is because a homoclinic orbit, although the net effect of the bifurcation is to create a homoclinic orbit, recent work has been stimulated by a series of papers [1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85, 86, 87, 88, 89, 90, 91, 92, 93, 94, 95, 96, 97, 98, 99, 100]. In certain conditions described below, there is chaotic behaviour.

on the linearized flow near the stationary point. Suppose that the stationary point is hyperbolic. Then, after a change of coordinates we may assume that it is at the origin for all values of μ which are of interest and the family of differential equations can be written in the form

$$\dot{x} = Ax + F(x, \mu) \tag{1}$$

for $x \in \mathbb{R}^n$, $n \geq 2$. Here $F(0, \mu) = 0$, A is a constant $n \times n$ matrix and F is smooth and contains only nonlinear terms. Assume that if $\mu = 0$ then the system has a homoclinic orbit $x_H(t)$ bicurcative

no homoclinic orbits close to x_H (by close we mean that for n sufficiently small $|x(t) - x_H(t)| < \epsilon$ for all $t \in (-\infty, \infty)$).

of n can be divided into two sets, $\{\lambda_i\}$, $i = 1, \dots, n_u$, and $\{\nu_j\}$, $j = 1, \dots, n_s$, $n_s + n_u = n$, such that $\text{Re}(\lambda_i) > 0$ and $\text{Re}(\nu_j) < 0$. These can be ordered so that

$$\text{Re}(\nu_1) \leq \dots \leq \text{Re}(\nu_s) \leq \text{Re}(\lambda_1) < \dots < \text{Re}(\lambda_n).$$

Typically, trajectories which tend to $x = 0$ as $t \rightarrow \infty$ do so tangential to the eigenspace corresponding to those eigenvalues with $\text{Re}(\nu_j) = \text{Re}(\nu_1)$, which we refer to as the dominant stable eigenvalues. Simi-

lars, trajectories which tend to $x = 0$ as $t \rightarrow -\infty$ do so tangential to the eigenspace corresponding to the dominant unstable eigenvalues, i.e. those with $\text{Re}(\lambda_j) = \text{Re}(\lambda_1)$. We assume that the homoclinic orbit, $x_H(t)$ is typical in this sense.

There are four generic cases (up to time reversal)

of dominant eigenvalues is $\{\nu_1, \lambda_1\}$, with $\nu_1, \lambda_1 \in \mathbb{R}$, and $\nu_1 + \lambda_1 \neq 0$.

In this case (which can occur for $n \geq 2$), provide some genericity conditions are satisfied, the homoclinic bifurcation creates a single periodic orbit which exists in either $\mu < 0$ or $\mu > 0$ [2]. As μ tends to zero from the appropriate side the periodic orbit

is stable if $\nu_1 + \lambda_1 < 0$, otherwise it is a saddle.

(II) *Saddle-focus homoclinic orbit.* The set of

dominant eigenvalues is $\{\nu_2, \nu_1, \lambda_1\}$, with $\nu_1 = \nu_2^* \in \mathbb{C} \setminus \mathbb{R}$, $\lambda_1 \in \mathbb{R}$, and $\text{Re}(\nu_1) + \lambda_1 \neq 0$.

This case can occur if $n \geq 3$. There are two subcases.

(IIa) $\text{Re}(\nu_1) + \lambda_1 < 0$. The bifurcation is essentially the same as case (I).

(IIb) $\text{Re}(\nu_1) + \lambda_1 > 0$. If $\mu = 0$ there are chaotic solutions in a tubular neighbourhood of the homoclinic orbit. There are sequences of saddle-node bifurcations accumulating on $\mu = 0$ from both sides, and sequences of (geometrically more complicated) homoclinic bifurcations accumulating on $\mu = 0$.

(III) *Bifocal homoclinic orbit.* The set of dominant eigenvalues is $\{\nu_1, \nu_2, \lambda_1, \lambda_2\}$ with $\nu_1 = \nu_2^* \in \mathbb{C} \setminus \mathbb{R}$ and $\lambda_1 = \lambda_2^* \in \mathbb{C} \setminus \mathbb{R}$.

Similar to that described for case (IIb), but typically there are more complicated homoclinic bifurcations accumulating on $\mu = 0$.

The results sketched above form the basis of

the study of the saddle-node, period-doubling and Hopf bifurcations in local bifurcation theory. Whilst there are many examples of cases (I) and (II) in the literature it is extraordinary that (to the best of our knowledge) no unambiguous examples of case (III) have been described to date. There are examples with homoclinic orbits to stationary points satisfying

the conditions of case (III), which have a very special bifurcation structure [11,12]. A piecewise linear example of case III is described in Ref. [13], and here we use the same ideas, described below, to construct a smooth (only

in one dimension) example of case III. In so doing we derive a hierarchy of equations in two, then three, and then four dimensions. Each equation is obtained from the previous system by extending it in an appropriate manner to one more dimension. In principle this construction could be extended to obtain a hierarchy of equations in higher dimensions.

Simple examples of interesting dynamical phenomena have been constructed using a variety of

techniques. Arnéodo, Coulet and Tresser [14] used

In coordinates (x_u, x_s, z) defined by $x = x_s e_s +$

the adjoint eigenvectors of the linear part of a "seed" equation to define the coupling between the equation and an extra variable in such a way that the linear part of the new equation has the desired spectral condition. We then appeal to perturbation theory and numerical experiment to suggest that the dynamically interesting behaviour (in this case, the existence of a homoclinic orbit) is inherited by the new equation from the "seed" equation. The new equation can in turn be treated as a "seed" equation and the process can be repeated. The use of adjoint eigenvectors is not entirely necessary (one could try trial and error) but ensures that complete control of the spectral properties of the stationary point is maintained throughout the hierarchy.

$$\dot{x}_u = \lambda_1 x_u, \quad \dot{x}_s = \nu_1 x_s - z, \quad \dot{z} = \epsilon_1 x_s + \nu_1 z, \quad (6)$$

with eigenvalues $\lambda_1 > 0$ and $\nu_1 \pm \sqrt{-\epsilon_1}$. Hence if $\epsilon_1 > 0$ the linear part of (3) satisfies the conditions of case (IIa). Since homoclinic bifurcations are typically of codimension one we expect (at least for small $\epsilon_1 > 0$) there to be a curve of homoclinic bifurcations in (μ, ϵ_1) parameter space of the form $\mu = H(\epsilon_1)$ with $H(0) = 0$. If this curve does exist then (5) provides an example of case (IIa).

Similarly, if we consider

$$\dot{w} = \epsilon_2 (e_u^\dagger \cdot x) + \lambda_1 w, \quad \dot{x} = Ax - we_u + f(x, \mu), \quad (7)$$

are easy to find, so let

$$\dot{x} = Ax + f(x, \mu) \quad (3)$$

and $\lambda_1 \pm \sqrt{-\epsilon_2}$ and so, using (4), under similar assumptions we obtain homoclinic bifurcations of class (III) in reverse time if $\epsilon_2 > 0$.

tion of the plane to itself which contains only nonlinear terms, $f(0, \mu) = 0$ and there is a homoclinic orbit, asymptotic to the stationary point at the constant 2×2 matrix A are ν_1 and λ_1 with $\nu_1 < 0 < \lambda_1$ and

$$\dot{w} = \epsilon_2 (e_u^\dagger \cdot x) + \lambda_1 w, \quad \dot{x} = \epsilon_1 (e_s^\dagger \cdot x) + \nu_1 x, \quad (8)$$

$$|\nu_1| > \lambda_1 \quad (4)$$

we should be able to find bifocal homoclinic bifurcations (case (III)) if ϵ_1 and ϵ_2 are small and positive.

eigenvectors (see e.g. Ref. [16] for a discussion of adjoint eigenvectors in dynamical systems). Thus $A^T e_s^\dagger = \nu_1 e_s^\dagger$, $A^T e_u^\dagger = \lambda_1 e_u^\dagger$, $e_s^\dagger \cdot e_u = e_u^\dagger \cdot e_s = 0$ and the eigenvectors can be normalized so that $e_s^\dagger \cdot e_s = e_u^\dagger \cdot e_u = 1$.

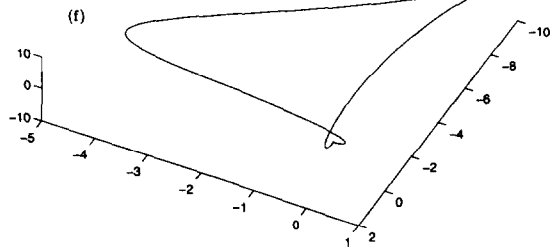
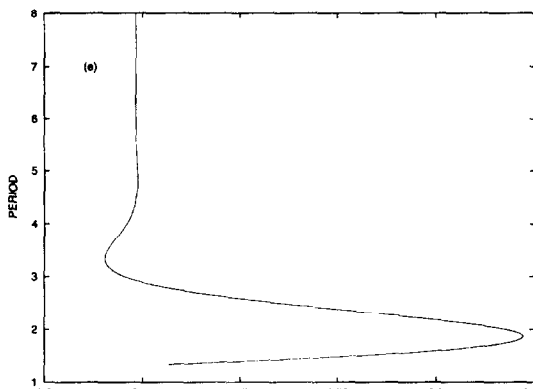
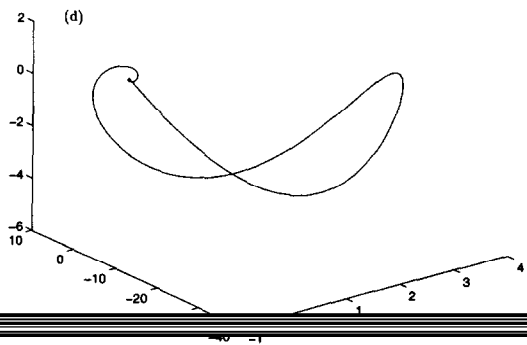
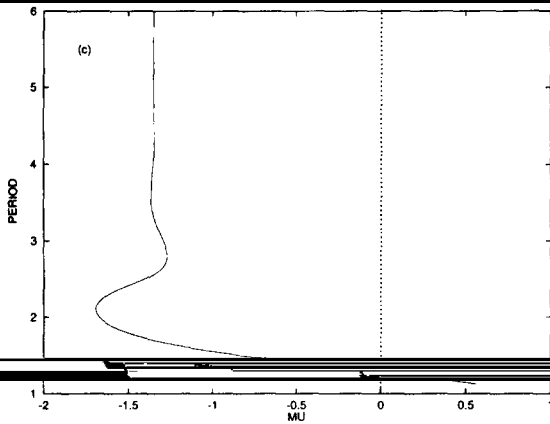
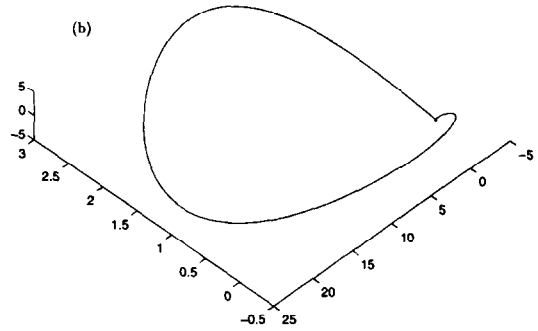
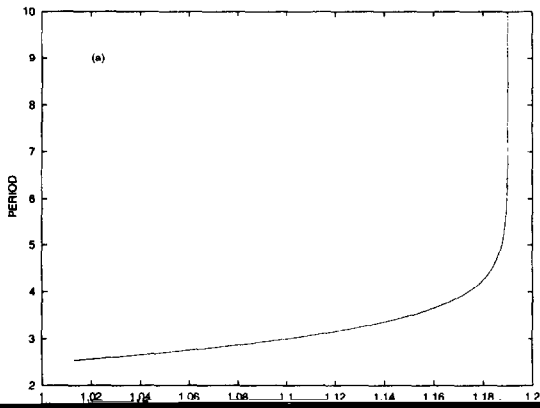
Eq. (3) is the first member of the homoclinic hierarchy. Now define the extended system

$$\text{dimensional system} \quad \dot{x} = y, \quad \dot{y} = 6x - y - 6x^2 + \mu xy, \quad (9)$$

$$\dot{x} = Ax - ze_s + f(x, \mu), \quad \dot{z} = \epsilon_1 (e_s^\dagger \cdot x) + \nu_1 z. \quad (5)$$

for which there is strong numerical evidence that a homoclinic orbit exists if $\mu = \mu_H \approx 1.164371$. For this example, in the notation of (3),

$$A = \begin{pmatrix} 0 & 1 \\ 6 & -1 \end{pmatrix}, \quad f(x, \mu) = \begin{pmatrix} 0 \\ -6x^2 + \mu xy \end{pmatrix}, \quad (10)$$



(a) Bifurcation diagram for Eq. (3) with $\epsilon = 0.1$ showing the approach of the simple periodic orbit to the homoclinic orbit. (b) A homoclinic orbit of (3) with $\mu = 16$ and $\nu = 2.557395$. (c) As (a) using Eq. (2) with $\mu = 16$. (d) A homoclinic orbit of (2) with $\mu = 16$ and $\nu = 1.251245$. (e) Bifurcation diagram for Eq. (3) with $\epsilon = 0.1$ showing the approach of the simple periodic orbit to the homoclinic orbit. (f) A homoclinic orbit of (3) with $\mu = 16$ and $\nu = 2.557395$.

tions and numerically obtained normalized eigenvectors, that for $0.55 < \mu < 0.64$ the signed distance function is positive (and equal to 0.004617 at $\mu = 0.64$ whilst for $0.65 < \mu < 0.71$ the signed distance function is negative (and equal to -0.002365 at $\mu = 0.65$). This strongly suggests that for some values of μ between 0.64 and 0.65 there is a zero of the distance function, and hence a homoclinic orbit for the differential equation (12). Linear interpolation between $\mu = 0.64$ and $\mu = 0.65$ gives an approximate value of $\mu = 0.645$ for the homoclinic bifurcation, in excellent agreement with the value obtained by following periodic orbits.

We have written down a hierarchy of differential equations which illustrate the four fundamental homoclinic bifurcations. In particular, we have obtained a smooth example of a bifocal homoclinic bifurcation (case III). So far as we are aware, this is the first such example (in Ref. [13] a piecewise linear example is studied, for which the existence of a bifocal homoclinic bifurcation can be proved using perturbation theory, but this does not satisfy the standard smoothness conditions of Shilnikov's results [13] although the results can be trivially ex-

are non-generic, having either a Hamiltonian or re-

The observant reader will have noted that one unfolding of the degenerate Jordan normal form

$$\begin{pmatrix} \lambda_1 & 1 & 0 & 0 \\ 0 & \lambda_1 & 0 & 0 \\ 0 & 0 & \nu_1 & 1 \\ 0 & 0 & 0 & \nu_1 \end{pmatrix} \quad (13)$$

We look at the existence of bifocal homoclinic orbits in this light elsewhere [8]: in particular, we explore several codimension two bifurcations involving bifocal homoclinic bifurcations. The normal form (13) has codimension greater than two, and we consider this to be too large for useful analysis in the absence of some concrete physical motivation.

C.L. is grateful to the Cambridge Commonwealth Trust for financial support.

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