

A homoclinic hierarchy

Paul Glendinning¹, Carlo Laing

Department of Applied Mathematics and Theoretical Physics, University of Cambridge, Silver Street, Cambridge CB3 9EW, UK

1 100# . 10 11

Communicated by A.P. Fordy

.

Abstract

Homoslinic hiturations in autonomous ordinary differential equations provide useful organizing contras for the analysis

AMS classification: 58F13; 58F14

Keywords: Bifurcation; Homoclinic orbit; Chaos

1001 1005

۰.

A homoclinic orbit of an autonomous ordinary

orbit which exists at $\mu = \mu_{\rm H}$. If this is the case we

......

	and $x_{\rm H}(0) \neq x_0$. In typical (e.g. non-Hamiltonian)	recent work has been stimulated by a series of papers
	tance of a homoglinic arbit is not a structurally stable	contain conditions described holess there is chartin
-	no longer have a nonlochine orbit close to the origi-	
	and a grich of any har har har him	<u></u>
	$\epsilon \setminus \{\mu_{\rm H}\}$ there is no homoclinic orbit close to the	cations, for which the homoclinic orbit loops several tipped through the tubular paighbourhood of the aria
	Serences, Queen many mile reserve concept, the Zne tone,	mine whather permitiented dynamics pacture are based

0375-9601/96/\$12.00 © 1996 Elsevier Science B.V. All rights reserved SSDI 0375-9601(95)00953-1

no homoclinic orbits close to $x_{\rm H}$ (by close we mean that for n sufficiently small $ x(t) = r_{\rm e}(t) \leq n$ for all $t \in (-\infty, \infty)$. If the construction of the set of domi- tion eigenvalues is $(n_1) = 1, \dots, n_n, n_n + n_u = n$, such that ${\sf Re}(\lambda_1)$ ${\sf Re}(t, t) \leq \dots \leq {\sf Re}(t, t) < 0$. The results sketched above form the basis of ${\sf Re}(t, t) \leq \dots \leq {\sf Re}(t, t) < 0$. The results sketched above form the basis of ${\sf Re}(t, t) \leq \dots \leq {\sf Re}(t, t) < 0$. The results sketched above form the basis of ${\sf Re}(t, t) \leq {\sf Re}(\lambda_2) \leq \dots \leq {\sf Re}(\lambda_n)$. Typically, trajectories which tend to $x = 0$ as $t \to \infty$ do so tangential to the eigenspace corresponding to those eigenvalues with ${\sf Re}(t, t) = {\sf Re}(t, t)$. We assume that the homoclinic orbit, $x_n(t)$ is typical in this sense. The set of dominant obtained for $n > 2$), provide some genericity conditions are satisfied, the homo- diric bifuenties extracted in the four dimensions. Each equation is obtained from the previous system by dimension. In principle this construction could be extended to obtain a hierarchy of equations in higher		on the linearized flow near the stationary point. Suppose that the stationary point is hyperbolic. Then, after a change of coordinates we may assume that it is at the origin for all values of μ which are of interest and the family of differential equations can be written in the form $\dot{x} = Ax + F(x, \mu)$ (1) for $x \in \mathbb{R}^n$, $n \ge 2$. Here $F(0, \mu) = 0$, A is a constant $n \times n$ matrix and F is smooth and contains only nonlinear terms. Assume that if $\mu = 0$ then the costam has a homeolinic orbit x (1) histormates	dominant eigenvalues is $\{\nu_2, \nu_1, \lambda_1\}$, with $\nu_1 = \nu_2^* \in \mathbb{C} \setminus \mathbb{R}, \lambda_1 \in \mathbb{R}$, and $\operatorname{Re}(\nu_1) + \lambda_1 \neq 0$. This case can occur if $n \ge 3$. There are two subcases. (IIa) $\operatorname{Re}(\nu_1) + \lambda_1 < 0$. The bifurcation is essentially the same as case (I). (IIb) $\operatorname{Re}(\nu_1) + \lambda_1 > 0$. If $\mu = 0$ there are chaotic solutions in a tubular neighbourhood of the homoclinic orbit. There are sequences of saddle-node bifurcations accumulating on $\mu = 0$ from both sides, and sequences of (geometrically more complicated)
and $\{\nu_i\}$, $i = 1,, n_s$, $n_s + n_u = n$, such that $\operatorname{Re}(\lambda_i)$ Ref $\nu_i > \ldots < \operatorname{Re}(\nu_s) < 0$. There are heredener by the form that $\operatorname{Re}(\lambda_i)$ $\operatorname{Re}(\nu_s) < \ldots < \operatorname{Re}(\lambda_1) < \operatorname{Re}(\lambda_2) < \ldots < \operatorname{Re}(\lambda_{n_u})$. Typically, trajectories which tend to $x = 0$ as $t \to \infty$ do so tangential to the eigenspace corresponding to those eigenvalues with $\operatorname{Re}(\nu_j) = \operatorname{Re}(\nu_1)$, which we refer to as the dominant unstance eigenvalues. Simi- sponding to the dominant unstance eigenvalues, i.e. those with $\operatorname{Re}(\lambda_j) = \operatorname{Re}(\lambda_1)$. We assume that the homoclinic orbit. $x_{ii}(t) = \operatorname{Re}(\lambda_1)$. We assume that the homoclinic orbit. $x_{ii}(t) = \operatorname{Re}(\lambda_1)$. We assume that the homoclinic orbit. $x_{ii}(t) = \operatorname{Re}(\lambda_1)$. We assume that the homoclinic orbit. $x_{ii}(t) = \operatorname{Re}(\lambda_1)$. We assume that the homoclinic orbit. $x_{ii}(t)$ is typical in this sense. Treff to as the dominant unstance eigenvalues, i.e. those with $\operatorname{Re}(\lambda_j) = \operatorname{Re}(\lambda_1)$. We assume that the homoclinic orbit. $x_{ii}(t)$ is typical in this sense. Treff to as the dominant unstance eigenvalues, i.e. those eigenvalues is $\{\nu_1, \lambda_1\}$, with ν_1 , $\lambda_1 \in \mathbb{R}$, and $\nu_1 + \lambda_1 \neq 0$. In this case (which can occur for $n \ge 2$), provide some genericity conditions are satisfied not be the existence of a bifocal homoclinic orbit. In so doing we derive a hierarchy of equations in two, then three, and then four dimensions. Each equation is obtained from the previous system by dimension. In principle this construction could be		<u>that for a sufficiently small $x(t) - x_n(t) < n$ for</u>	nant eigenvalues is $\{u, v, \lambda, \lambda\}$ with $v = v^* \in$
$\operatorname{Re}(\lambda_1) \leq \operatorname{Re}(\lambda_2) \leq \ldots \leq \operatorname{Re}(\lambda_{n_u}).$ $\operatorname{Re}(\lambda_1) \leq \operatorname{Re}(\lambda_2) \leq \ldots \leq \operatorname{Re}(\lambda_{n_u}).$ $about the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the set many chaines in the saddle-node, period-doubling and Hopf bifurcation is local bifurcation in the set many chaines in the set many chaines in the saddle-node, period-doubling and Hopf bifurcation is bifurcation in the set many chaines in the set many c$	-		
Typically, trajectories which tend to $x = 0$ as $t \to \infty$ do so tangential to the eigenspace corresponding to those eigenvalues with $\operatorname{Re}(\nu_j) = \operatorname{Re}(\nu_1)$, which we refer to as the dominant stable eigenvalues. Simi- sponding to the dominant unstable eigenvalues. Simi- those with $\operatorname{Re}(\lambda_j) = \operatorname{Re}(\lambda_1)$. We assume that the homoclinic orbit. $x_{in}(t)$ is typical in this sense. Trajector four corrector correct on the time reverse. Trajector four corrector correct on the time reverse. In this case (which can occur for $n \ge 2$), provide some genericity conditions are satisfied, the homo- eligic bifurcation correct on the previous system by exists in either $\mu < 0$ or $\mu > 0$ [2]. As μ tends to		$\operatorname{Re}(\nu) \leq \ldots \leq \operatorname{Re}(\nu_{0}) \leq \operatorname{Re}(\nu_{0}) < 0$	The results sketched above form the basis of
Typically, trajectories which tend to $x = 0$ as $t \to \infty$ do so tangential to the eigenspace corresponding to those eigenvalues with $\operatorname{Re}(\nu_j) = \operatorname{Re}(\nu_1)$, which we refer to as the dominant stable eigenvalues. Simi- sponding to the dominant distable eigenvalues. Simi- those with $\operatorname{Re}(\lambda_j) = \operatorname{Re}(\lambda_1)$. We assume that the homoclinic orbit, $x_{\mathrm{H}}(t)$ is typical in this sense. Trage are four corresponding to the time reverse) inant eigenvalues is $\{\nu_1, \lambda_1\}$, with $\nu_1, \lambda_1 \in \mathbb{R}$, and $\nu_1 + \lambda_1 \neq 0$. In this case (which can occur for $n \ge 2$), provide some genericity conditions are satisfied, the homo- olicit bifurction entering entering entering entering to the previous system by exists in either $\mu < 0$ or $\mu > 0$ [2]. As μ tends to		$< \operatorname{Re}(\lambda_1) \leq \operatorname{Re}(\lambda_2) \leq \ldots \leq \operatorname{Re}(\lambda_{n_u}).$	
those with $\operatorname{Re}(\lambda_j) = \operatorname{Re}(\lambda_1)$. We assume that the homoclinic orbit. $x_{II}(t)$ is typical in this sense.[11,12]. A piecewise linear example of case III is described in Ref. [13]. and here we use the same described heles. It constructs construct a construct of case III is described in Ref. [13]. and here we use the same ideas described heles. It constructs construct a construct of case III is described in Ref. [13]. and here we use the same ideas described heles. It constructs construct a construct of case III is described in Ref. [13]. and here we use the same ideas described heles. It constructs construct a construct of case III is described heles. It constructs a construct a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is evidence for the existence of a bifocal homoclinic orbit. In so doing we derive a hierarchy of equations in two, then three, and then four dimensions. Each equation is obtained from the previous system by extending it is construction could beexists in either $\mu < 0$ or $\mu > 0$ [2]. As μ tends todimension. In principle this construction could be		do so tangential to the eigenspace corresponding to those eigenvalues with $\text{Re}(\nu_j) = \text{Re}(\nu_1)$, which we	literature it is extraordinary that (to the best of our knowledge) no unambiguous examples of case (III) have been described to date. There are examples
those with $\operatorname{Re}(\lambda_j) = \operatorname{Re}(\lambda_1)$. We assume that the homoclinic orbit. $x_{II}(t)$ is typical in this sense.[11,12]. A piecewise linear example of case III is described in Ref. [13]. and here we use the same described heles. It constructs construct a construct of case III is described in Ref. [13]. and here we use the same ideas described heles. It constructs construct a construct of case III is described in Ref. [13]. and here we use the same ideas described heles. It constructs construct a construct of case III is described in Ref. [13]. and here we use the same ideas described heles. It constructs construct a construct of case III is described heles. It constructs a construct a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is described heles. It constructs a construct of case III is evidence for the existence of a bifocal homoclinic orbit. In so doing we derive a hierarchy of equations in two, then three, and then four dimensions. Each equation is obtained from the previous system by extending it is construction could beexists in either $\mu < 0$ or $\mu > 0$ [2]. As μ tends todimension. In principle this construction could be			
inant eigenvalues is $\{\nu_1, \lambda_1\}$, with $\nu_1, \lambda_1 \in \mathbb{R}$, and $\nu_1 + \lambda_1 \neq 0$. In this case (which can occur for $n \ge 2$), provide some genericity conditions are satisfied, the homo- clinic bifurction excites a sincle periodic orbit which exists in either $\mu < 0$ or $\mu > 0$ [2]. As μ tends to		those with $\text{Re}(\lambda_j) = \text{Re}(\lambda_1)$. We assume that the homoclinic orbit, $x_{\text{tr}}(t)$ is typical in this sense.	[11,12]. A piecewise linear example of case III is described in Ref. [13], and here we use the same
exists in either $\mu < 0$ or $\mu > 0$ [2]. As μ tends to dimension. In principle this construction could be		inant eigenvalues is $\{\nu_1, \lambda_1\}$, with $\nu_1, \lambda_1 \in \mathbb{R}$, and $\nu_1 + \lambda_1 \neq 0$. In this case (which can occur for $n \ge 2$), provide some genericity conditions are satisfied, the homo-	orbit. In so doing we derive a hierarchy of equations in two, then three, and then four dimensions. Each
		exists in either $\mu < 0$ or $\mu > 0$ [2]. As μ tends to	

stable if $\nu_1 + \lambda_1 < 0$, otherwise it is a saddle. (II) Saddle-focus homoclinic orbit. The set of Simple examples of interesting dynamical phenomena have been constructed using a variety of

. .

techniques. Arnéodo, Coullet and Tresser [14] used	In coordinates (x_u, x_s, z) defined by $x = x_s e_s + \frac{1}{2}$
the adjoint eigenvectors of the linear part of a "seed" <u>apprention</u> to define the experime between the equation and an extra variable in such a way that the linear part of the new equation has the desired spectral condition. We then appeal to perturbation theory and numerical experiment to suggest that the dynami-	$\dot{x}_u = \lambda_1 x_u$, $\dot{x}_s = \nu_1 x_s - z$, $\dot{z} = \epsilon_1 x_s + \nu_1 z$, (6) with eigenvalues $\lambda_1 > 0$ and $\nu_1 \pm \sqrt{-\epsilon_1}$. Hence if $\epsilon_1 > 0$ the linear part of (3) satisfies the conditions of case (IIa). Since homoclinic bifurcations are typically of codimension one we expect (at least for appell $\epsilon_1 > 0$) there to be a current of homoclinic
of a homoclinic orbit) is inherited by the new equa-	bifurcations in (μ, ϵ_1) parameter space of the form $\mu = H(\epsilon_1)$ with $H(0) = 0$ If this curve does exist
can in turn be treated as a "seed" equation and the process can be repeated. The use of adjoint eigenvec- tors is not entirely necessary (one could try trial and error) but ensures that complete control of the spec-	then (5) provides an example of case (11a). Similarly, if we consider $\dot{w} = \epsilon_2 (e_u^{\dagger} \cdot x) + \lambda_1 w$,
tral properties of the stationary point is maintained	$\dot{\mathbf{x}} = A\mathbf{x} - w\mathbf{e}_{u} + f(\mathbf{x}, \mu), \qquad (7)$
are easy to find, so let	and $\lambda_1 \pm \sqrt{-\epsilon_2}$ and so, using (4), under similar
$\dot{x} = A x + f(x, \mu) \tag{3}$	assumptions we obtain homoclinic bifurcations of

tion of the plane to itself which contains only nonlinear terms, $f(0, \mu) = 0$ and there is a homoclinic orbit biccumptotic to the stationary point at the

 $< \lambda_1$ and

$$\dot{w} = \epsilon_2 (e_u^{\dagger} \cdot x) + \lambda_1 w,$$

~ _ _ _

we should be able to find bifocal homoclinic bifurcations (case (III)) if ϵ and ϵ are small and positive

eigenvectors (see e.g. Ref. [16] for a discussion of adjoint eigenvectors in dynamical systems). Thus $A^{T}e_{s}^{\dagger} = \nu_{1}e_{s}^{\dagger}$, $A^{T}e_{u}^{\dagger} = \lambda_{1}e_{u}^{\dagger}$, $e_{s}^{\dagger} \cdot e_{u} = e_{u}^{\dagger} \cdot e_{s} = 0$ and the eigenvectors can be normalized so that $e_{s}^{\dagger} \cdot e_{s} = e_{u}^{\dagger} \cdot e_{u} = 1$.

NOW RELEASING & DELEGENTATION OF

Eq. (3) is the first member of the homoclinic hierarchy. Now define the extended system

$$\dot{\mathbf{x}} = A\mathbf{x} - z\mathbf{e}_{s} + f(\mathbf{x}, \ \mu),$$

$$\dot{z} = \epsilon_{1}(\mathbf{e}_{s}^{\dagger} \cdot \mathbf{x}) + \nu_{1}z.$$
 (5)

dimensional system

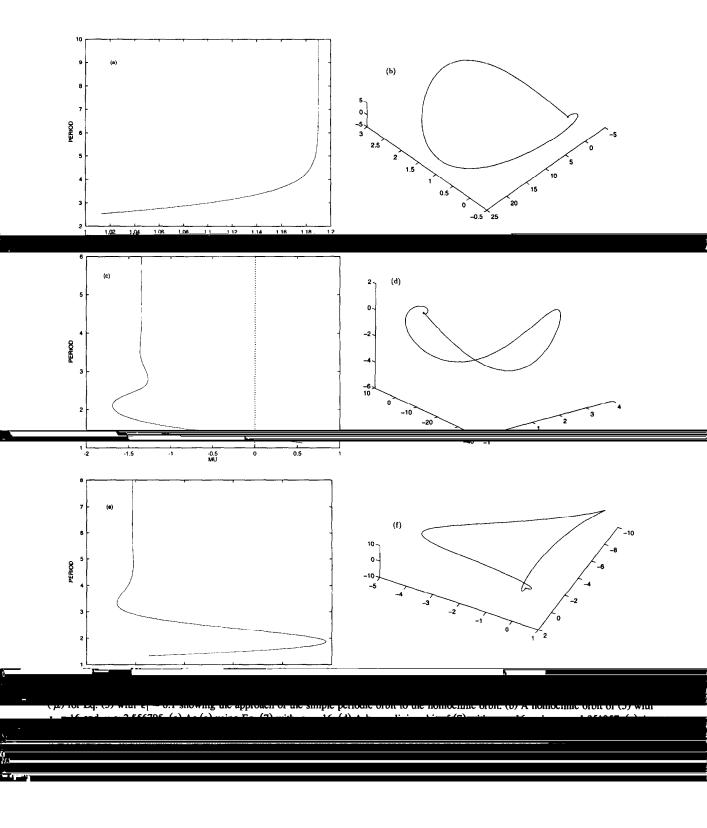
-1(°s

$$\dot{x} = y, \quad \dot{y} = 6x - y - 6x^2 + \mu xy,$$
 (9)

for which there is strong numerical evidence that a homoclinic orbit exists if $\mu = \mu_{\rm H} \approx 1.164371$. For this example, in the notation of (3),

$$A = \begin{pmatrix} 0 & 1 \\ 6 & -1 \end{pmatrix}, \quad f(x, \mu) = \begin{pmatrix} 0 \\ -6x^2 + \mu xy \end{pmatrix},$$
(10)

157



s_{α} $\lambda = 2$ $\mu = -3$ and (4) is satisfied A simple	the periodic orbit to a bifacal homoclinic orbit
$ \frac{1}{1} 1$	homoclinic orbit.
$\dot{w} = \epsilon_2(3x+y) + 2w, \dot{x} = y - \frac{1}{5}z - \frac{1}{5}w,$ $\dot{y} = \dot{o}x - y + \frac{3}{5}z - \frac{2}{5}w - 6x^2 + \mu xy,$ (11)	follow a periodic orbit to very high period provides very strong evidence for the existence of the homo- clinic orbit, but we have also done turner numerical experiments to add more weight to our claim. The local stable manifold of the origin is tangential to the plane spanned by $e_1 = (0, 0, 0, 1)^T$ and e_s (extended
Although our argument for the existence of homo- clinic orbits in (12) (and hence (5) and (7)) is	manifold is tangential to the plane spanned by e_u (extended to \mathbb{R}^4) and $e_4 = (1, 0, 0, 0)^T$. If a homo-
$ \epsilon_i $ (<i>i</i> = 1, 2). We use larger values of the parame-	that a point of intersection lies in the hyperplane
features of the orbits, in particular the spiralling motion near the stationary point, is much clearer at these values. In all cases, the approximate parameter	of this intersection we integrated points on a circle of initial conditions enclosing the origin on the linear approximation to the local unstable manifold for-
high period with changing parameter. The homo- clinic orbit can be thought of as the limit of this orbit as the period tends to infinity. Fig. 1 shows the results of three sets of numerical experiments obtained using AUTO [17]. In Figs. 1a, 1b we have set $\epsilon_2 = w = 0$ (equivalent to choosing (5) with A and f given by (10) and the adjoint	2 < x < 2.5 (if such an intersection exists). In this way we obtained a series of points on a curved line segment, U. A similar exercise in reverse time using initial conditions on the linear approximation to the local stable manifold provided a second curved line segment, S. This numerical experiment was repeated at different values of μ . Using polynomial interpola- tion to obtain expressions for U and S between
illustrating the familiar logarithmic increase in period as the orbit approaches the homoclinic orbit in case (IIa) with $\epsilon_1 = 0.1$. In Fig. 1b we show a homoclinic orbit for this system with $\epsilon_1 = 16$ and	was calculated using Newton's method on the parametrized curves. Now let n be the vector ob- tained in this way with $\mu = 0.64$, and $u(\mu)$ the vector obtained at nearby values of μ . These results
Figs. 1c, 1d shows similar plots for $\epsilon_1 = z = 0$ and $\epsilon_2 = 16$ (equivalent to (7): $z = 0$ is an invariant manifold). In this case, as expected for (IIb), the periodic orbit undergoes a sequence of saddle-node bifurcations as its period tends to infinity. The homo- clinic orbit at $\mu \approx -1.351357$ is illustrated in Fig. 1d. Finally, Figs. 1e, 1f show the analogous pictures	sign $(n \cdot u(\mu)) u(\mu) $. A zero of this signed distance function thus indicates an intersection between S and U, and hence the existence of a homoclinic orbit. If, in addition, the sign of the signed distance function changes, then the family of differential equations parametrized by μ passes transversely through the codimension one surface of systems with homoclinic orbits. We found,

159

tions and numerically obtained normalized eigenvectors, that for $0.55 < \mu < 0.64$ the signed distance function is positive (and equal to 0.004617 at $\mu = 0.64$ whilst for $0.65 < \mu < 0.71$ the signed distance function is negative (and equal to -0.002365 at $\mu = 0.65$). This strongly suggests that for some values of μ between 0.64 and 0.65 there is a zero of the distance function, and hence a homoclinic orbit for the differential equation (12). Linear interpolation

cation, in excellent agreement with the value obtained by following periodic orbits.

We have written down a hierarchy of differential equations which illustrate the four fundamental homoclinic bifurcations. In particular, we have obtained a smooth example of a bifocal homoclinic bifurcation (case (III)). So far as we are aware, this is the first such example (in Ref. [13] a piecewise linear example is studied, for which the existence of a bifocal homoclinic bifurcation can be proved using perturbation theory, but this does not satisfy the standard smoothness conditions of Shilnikov's results [13] although the results can be trivially exWe look at the existence of bifocal homoclinic orbits in this light elsewhere [8]: in particular, we explore several codimension two bifurcations involving bifocal homoclinic bifurcations. The normal form (13) has codimension greater than two, and we consider this to be too large for useful analysis in the absence of some concrete physical motivation.

C.L. is grateful to the Cambridge Commonwealth

References

- [1] L.P. Shilnikov, Sov. Math. Dokl. 6 (1965) 163.
- [2] L.P. Shilnikov, Math. USSR Sb. 6 (1968) 427.
- [3] L.P. Shilnikov, Math. USSR Sb. 10 (1970) 91.
- [4] P. Glendinning and C. Sparrow, J. Stat. Phys. 35 (1984) 645.
- [5] P. Gaspard, R. Kapral and G. Nicolis, J. Stat. Phys. 35 (1984) 697.
- [6] P. Gaspard, Phys. Lett. A 97 (1984) 1.
- [7] P. Glendinning, Math. Proc. Cambridge Philos. Soc. 105 (1989) 597.
- [8] C. Laing and P. Glendinning, in preparation (1995).
- [9] C. Tresser, Ann. Inst. H. Poincaré 40 (1984) 441.

r'____

are non-generic, having either a Hamiltonian or re-	[12] A.R. Champneys and J.F. Toland, Nonlinearity 6 (1993) 665.
The observant reader will have noted that one	[14] A. Améodo, P. Coullet and C. Tresser, J. Stat. Phys. 27
$ \begin{pmatrix} \lambda_{1} & 1 & 0 & 0 \\ 0 & \lambda_{1} & 0 & 0 \\ 0 & 0 & \nu_{1} & 1 \\ 0 & 0 & 0 & \nu_{1} \end{pmatrix} $ (13)	 [16] P. Glendinning, Stability, instability and chaos: an introduction to the qualitative theory of ordinary differential equations (Cambridge Univ. Press, Cambridge, 1994). [17] E.J. Doedel and J.P. Kernevez, AUTO: Software for continuation and bifurcation problems in ordinary differential equations, Report, Applied Mathematics, California Institute of Technology (1986).